

# OpenMP for Accelerators

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- **What is an Accelerator?**
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# What is an Accelerator?

in OpenMP

# What kind of devices shall be supported?



## ■ In how differs an accelerator from just another core?

- different functionality, i.e. optimized for something special
- different (possibly limited) instruction set
- heterogeneous device

## ■ Assumptions used as design goals for OpenMP 4.0:

- every accelerator device is attached to one host device
- it is probably heterogeneous
- it may not be programmable in the same language as the host, or it may not implement all operations available on the host
- it may or may not share memory with the host device
- some accelerators are specialized for loop nests



# Execution and Data Model

- **Host-centric: the execution of an OpenMP program starts on the *host device* and it may offload *target regions* to *target devices***
  - In principle, a target region also begins as a single thread of execution: when a target construct is encountered, the target region is executed by the implicit device thread and the encountering thread/task [on the host] waits at the construct until the execution of the region completes
- **If a target device is not present, or not supported, or not available, the target region is executed by the host device**
- **If a construct creates a *data environment*, the data environment is created at the time the construct is encountered**

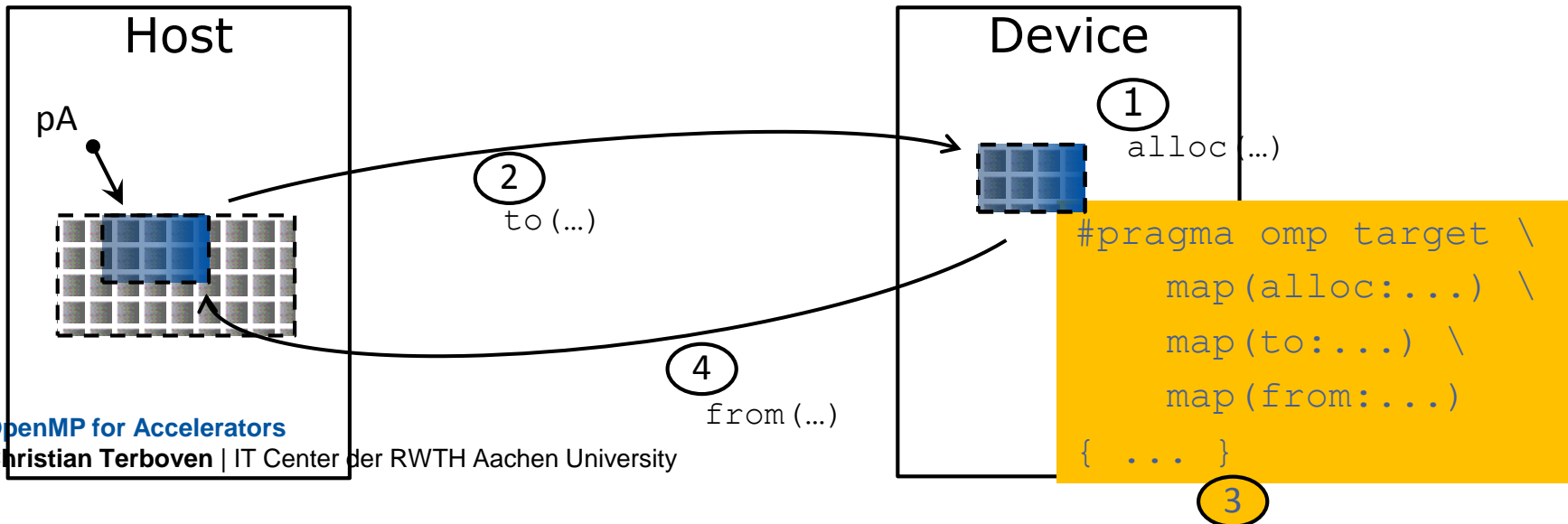
- **When an OpenMP program begins, each device has an initial *device data environment***
- **Directives accepting data-mapping attribute clauses determine how an *original* variable is mapped to a *corresponding* variable in a device data environment**
  - original: the variable on the host
  - corresponding: the variable on the device
  - the corresponding variable in the device data environment may share storage with the original variable (danger of data races)
- **If a corresponding variable is present in the enclosing device data environment, the new device data environment inherits the corresponding variable from the enclosing device**

## ■ Data environment is lexically scoped

- Data environment is destroyed at closing curly brace
- Allocated buffers/data are automatically released

## ■ Use target construct to

- Transfer control from the host to the device
- Establish a data environment (if not yet done)
- Host thread waits until offloaded region completed





```
#pragma omp target data device(0) map(alloc:tmp[:N])
    map(to:input[:N]) map(from:res)
{
#pragma omp target device(0)
#pragma omp parallel for
    for (i=0; i<N; i++)
        tmp[i] = some_computation(input[i], i);

    do_some_other_stuff_on_host();

#pragma omp target device(0)
#pragma omp parallel for reduction(+:res)
    for (i=0; i<N; i++)
        res += final_computation(tmp[i], i)
}
```

data region

shaping and slicing

offload

host

target

host

target

host

- This is a very simple example, but you see functionality similar to OpenACC 1.0. Device support has to come with the implementation.

- **Environment Variable OMP\_DEFAULT\_DEVICE=<int>: sets the device number to use in target constructs**

```
double B[N] = ...; // some initialization
#pragma omp target device(0) map(tofrom:B)
#pragma omp parallel for
for (i=0; i<N; i++)
    B[i] += sin(B[i]);
```

→ map variable B to device, then execute parallel region on device, works probably pretty well on Intel Xeon Phi

```
double B[N] = ...; // some initialization
#pragma omp target device(0) map(tofrom:B)
#pragma omp teams num_teams(num_blocks) num_threads(bsize)
#pragma omp distribute
for (i=0; i<N; i += num_blocks)
    #pragma omp parallel for
    for (b = i; b < i+bsize; b++)
        B[b] += sin(B[b]);
```

→ same as above, but code probably better optimized for NVIDIA GPGPUs

## ■ OpenMP 4.0 – for Intel Xeon Phi:

```
#pragma omp target device(0) map(tofrom:B)
#pragma omp parallel for
for (i=0; i<N; i++)
    B[i] += sin(B[i]);
```

## ■ OpenMP 4.0 – for NVIDIA GPGPU:

```
#pragma omp target device(0) map(tofrom:B)
#pragma omp teams num_teams(num_blocks) num_threads(bsize)
#pragma omp distribute
for (i=0; i<N; i += num_blocks)
    #pragma omp parallel for
    for (b = i; b < i+num_blocks; b++)
        B[b] += sin(B[b]);
```

## ■ OpenACC **Also possible (and equivalent) in OpenMP 4.0:**

```
#pragma acc parallel copy(B[0:N]) num_gangs(numblocks) \
    vector(numthreads)
Combined directive
#pragma acc loop gang vector
#pragma omp teams distribute parallel for
for (i=0; i<N; ++i) {
    B[i] += sin(B[i]);
}
```

# Target Construct

## ■ Creates a device data environment for the extent of the region

- when a target data construct is encountered, a new device data environment is created, and the encountering task executes the target data region
- when an if clause is present and the if-expression evaluates to false, the device is the host

## ■ C/C++:

The syntax of the **target data** construct is as follows:

```
#pragma omp target data [clause[[,] clause],...] new-line  
structured-block
```

where *clause* is one of the following:

```
device( integer-expression )  
map( [map-type : ] list )  
if( scalar-expression )
```

- **Map a variable from the current task's data environment to the device data environment associated with the construct**
  - the list items that appear in a map clause may include array sections
  - **alloc**-type: each new corresponding list item has an undefined initial value
  - **to**-type: each new corresponding list item is initialized with the original list item's value
  - **from**-type: declares that on exit from the region the corresponding list item's value is assigned to the original list item
  - **tofrom**-type: the default, combination of to and from

## ■ C/C++:

The syntax of the **map** clause is as follows:

```
map( [map-type : ] list )
```

- **Creates a device data environment and execute the construct on the same device**

→ superset of the target data constructs - in addition, the target construct specifies that the region is executed by a device and the encountering task waits for the device to complete the target region

- **C/C++:**

The syntax of the **target** construct is as follows:

```
#pragma omp target [clause[[, clause],...] new-line  
structured-block
```

where *clause* is one of the following:

```
device( integer-expression )  
map( [map-type : ] list )  
if( scalar-expression )
```

Note: map clause does not work correctly with Intel 14.0 compilers

- **Makes the corresponding list items in the device data environment consistent with their original list items, according to the specified motion clauses**

- **C/C++:**

The syntax of the **target update** construct is as follows:

```
#pragma omp target update motion-clause[, clause[[,] clause],...] new-line
```

where *motion-clause* is one of the following:

```
to( list )  
from( list )
```

and where *clause* is one of the following:

```
device( integer-expression )  
if( scalar-expression )
```



- **Specifies that [static] variables, functions (C, C++ and Fortran) and subroutines (Fortran) are mapped to a device**
  - if a list item is a function or subroutine then a device-specific version of the routines is created that can be called from a target region
  - if a list item is a variable then the original variable is mapped to a corresponding variable in the initial device data environment for all devices (if the variable is initialized it is mapped with the same value)
  - all declarations and definitions for a function must have a declare target directive

## ■ C/C++:

The syntax of the **declare target** directive is as follows:

```
#pragma omp declare target new-line  
declarations-definition-seq  
#pragma omp end declare target new-line
```

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# Example: Target Construct



```
#pragma omp target device(0)
#pragma omp parallel for
    for (i=0; i<N; i++) ...
```

```
#pragma omp target
#pragma omp teams num_teams(8) num_threads(4)
#pragma omp distribute
    for ( k = 0; k < NUM_K; k++ )
    {
        #pragma omp parallel for
        for ( j = 0; j < NUM_J; j++ )
        {
            ...
        }
    }
```

- **Creates a league of thread teams where the master thread of each team executes the region**
  - the number of teams is determined by the `num_teams` clause, the number of threads in each team is determined by the `num_threads` clause, within a team region team numbers uniquely identify each team (`omp_get_team_num()`)
  - once created, the number of teams remains constant for the duration of the teams region
- **The teams region is executed by the master thread of each team**
- **The threads other than the master thread do not begin execution until the master thread encounters a parallel region**
- **Only the following constructs can be closely nested in the team region: distribute, parallel, parallel loop/for, parallel sections and parallel workshare**

- **Specifies that the iteration of one or more loops will be executed by the thread teams, the iterations are distributed across the master threads of all teams**
  - there is no implicit barrier at the end of a distribute construct
  - a distribute construct must be closely nested in a teams region

## ■ C/C++:

The syntax of the **distribute** construct is as follows:

```
#pragma omp distribute [clause[[,] clause],...] new-line  
for-loops
```

Where *clause* is one of the following:

```
private( list )  
firstprivate( list )  
collapse( n )  
dist_schedule( kind[, chunk_size] )
```

All associated for-loops must have the canonical form described in Section 2.5.

- A teams construct must be contained within a target construct, which must not contain any statements or directives outside of the teams construct
- After the teams have completed execution of the teams region, the encountering thread resumes execution of the enclosing target region

- **C/C++:**

The syntax of the **teams** construct is as follows

```
#pragma omp teams [clause[[, clause],...] new-line  
structured-block
```

where *clause* is one of the following:

```
num_teams( integer-expression )  
num_threads( integer-expression )  
default(shared | none)  
private( list )  
firstprivate( list )  
shared( list )  
reduction( operator : list )
```

# Example: SAXPY

# SAXPY: Serial (Host)



```
int main(int argc, const char* argv[]) {
    int n = 10240; float a = 2.0f; float b = 3.0f;
    float *x = (float*) malloc(n * sizeof(float));
    float *y = (float*) malloc(n * sizeof(float));
    // Initialize x, y

    // Run SAXPY TWICE

    for (int i = 0; i < n; ++i){
        y[i] = a*x[i] + y[i];
    }

    // y is needed and modified on the host here

    for (int i = 0; i < n; ++i){
        y[i] = b*x[i] + y[i];
    }

    free(x); free(y); return 0;
}
```

```
int main(int argc, const char* argv[]) {
    int n = 10240; float a = 2.0f; float b = 3.0f;
    float *x = (float*) malloc(n * sizeof(float));
    float *y = (float*) malloc(n * sizeof(float));
    // Initialize x, y

    // Run SAXPY TWICE
#pragma acc data copyin(x[0:n])
{

#pragma acc parallel copy(y[0:n])
#pragma acc loop
    for (int i = 0; i < n; ++i){
        y[i] = a*x[i] + y[i];
    }
    // y is needed and modified on the host here
#pragma acc parallel copy(y[0:n])
#pragma acc loop
    for (int i = 0; i < n; ++i){
        y[i] = b*x[i] + y[i];
    }
}
    free(x); free(y); return 0;
}
```



```
int main(int argc, const char* argv[]) {
    int n = 10240; float a = 2.0f; float b = 3.0f;
    float *x = (float*) malloc(n * sizeof(float));
    float *y = (float*) malloc(n * sizeof(float));
    // Initialize x, y

    // Run SAXPY TWICE
#pragma omp target data map(to:x[0:n])
{
#pragma omp target map(tofrom:y[0:n])
#pragma omp parallel for
for (int i = 0; i < n; ++i){
    y[i] = a*x[i] + y[i];
}

    // y is needed and modified on the host here
#pragma omp target map(tofrom:y[0:n])
#pragma omp parallel for
    for (int i = 0; i < n; ++i){
        y[i] = b*x[i] + y[i];
    }
}
    free(x); free(y); return 0;
}
```

# SAXPY: OpenMP 4.0 (NVIDIA GPGPU)



```
int main(int argc, const char* argv[]) {
    int n = 10240; float a = 2.0f; float b = 3.0f;
    float *x = (float*) malloc(n * sizeof(float));
    float *y = (float*) malloc(n * sizeof(float));
    // Initialize x, y

    // Run SAXPY TWICE
#pragma omp target data map(to:x[0:n])
{
#pragma omp target map(tofrom:y[0:n])
#pragma omp teams
#pragma omp distribute
#pragma omp parallel for
for (int i = 0; i < n; ++i){
    y[i] = a*x[i] + y[i];
}
    // y is needed and modified on the host here
#pragma omp target map(tofrom:y[0:n])
#pragma omp teams
#pragma omp distribute
#pragma omp parallel for
    for (int i = 0; i < n; ++i){
        y[i] = b*x[i] + y[i];
    }
    free(x); free(y); return 0;
}
```



# Live Experiment: PI

## ■ Host version

```
double f(double x) {
    return (double)4.0 / ((double)1.0 + (x*x));
}

void computePi() {
    double h = (double)1.0 / (double)iNumIntervals;
    double sum = 0, x;

#pragma omp parallel for private(x) reduction(+:sum)
    for (int i = 1; i <= iNumIntervals; i++) {
        x = h * ((double)i - (double)0.5);
        sum += f(x);
    }
    myPi = h * sum;
}
```

## ■ Accelerator version (Intel Xeon Phi)

**#pragma omp declare target**

```
double f(double x) {  
    return (double)4.0 / ((double)1.0 + (x*x));  
}
```

```
void computePi() {  
    double h = (double)1.0 / (double)iNumIntervals;  
    double sum = 0, x;
```

**#pragma omp target**

**#pragma omp parallel for private(x) reduction(+:sum)**

```
    for (int i = 1; i <= iNumIntervals; i++) {  
        x = h * ((double)i - (double)0.5);  
        sum += f(x);  
    }  
    myPi = h * sum;  
}
```

# PI on Host and Accelerator



# Outlook

- **OpenMP 4.0 introduced the `target` construct for device programming, i.e. compute accelerators – some aspects were missing / undefined:**
  - combinations of constructs, `#pragma omp target teams distribute parallel for simd`
  - concurrent mapping of the same variable by two threads – still undefined
- **Current Plans for OpenMP 4.1:**
  - async execution: currently the host waits for `target` operation to complete
    - `task target` construct: asyn offload, host will continue execution
    - dependencies between host and device: adding `target` will maintain them
  - unstructured data movement: sometimes data regions are too static
    - `target enter data / exit data` constructs to push / pull at encountering
  - open discussion on support for multiple devices (i.e. work distribution)



# The End

**Thank you for your attention.**