

# Introduction to OpenCL

**with GPGPUs**

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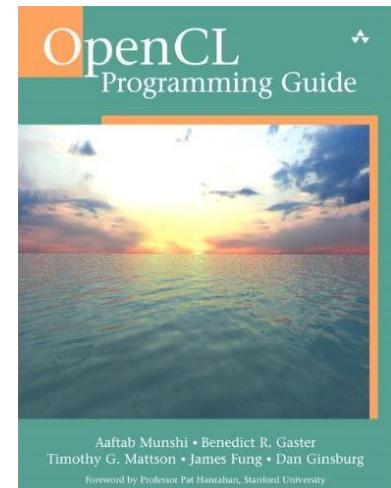
## ▶ General

- ▶ GPGPU Community: <http://gpgpu.org/>
- ▶ GPU Computing Community: <http://gpucomputing.net/>

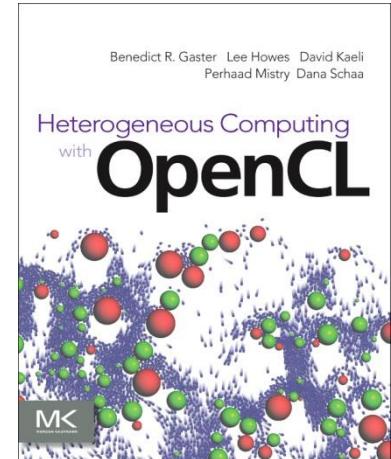
## ▶ OpenCL

- ▶ Khronos Group (Specification, Reference Pages,...):  
<http://www.khronos.org/opencl/>
- ▶ OpenCL + Nvidia <http://developer.nvidia.com/opencl>
- ▶ OpenCL + AMD: <http://developer.amd.com/zones/openclzone>
- ▶ OpenCL + Intel: <http://software.intel.com/en-us/articles/opencl-sdk/>

- ▶ **A. Munshi, B. Gaster, T. Mattson, J. Fung, D. Ginsburg: *OpenCL Programming Guide* (2011)**



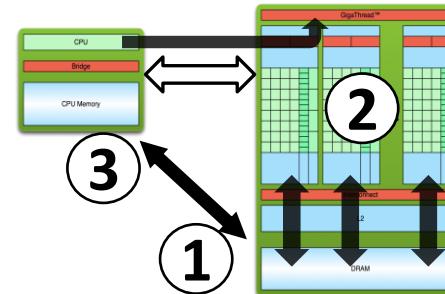
- ▶ **B. Gaster, D. Kaeli, L. Howes, P. Mistry, D. Schaa: *Heterogeneous Computing with OpenCL* (2011)**



- ▶ **Overview**
- ▶ **Programming Model**
- ▶ **Platform Model**
- ▶ **Execution Model**
- ▶ **Memory Model**
- ▶ **Summary**
- ▶ **Tools & Libs**

## ▶ Processing flow

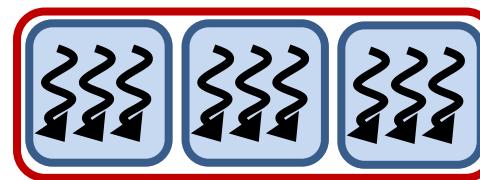
- ▶ Copy data from host to device
- ▶ Execute GPU code (kernel) in parallel
- ▶ Copy data from device to host



## ▶ CUDA: Kernel executes grid of blocks of threads

## ▶ CUDA memory hierarchy on GPU

- ▶ Thread: registers, local
- ▶ Block: shared
- ▶ Grid: global



- = **Open Computing Language**
- ▶ **Portable, parallel programming of heterogeneous parallel computing CPUs, GPUs, and other processors**
- ▶ **Open industry standard by Khronos group**
  - AMD **NVIDIA**, Intel, Apple, Ericsson, Nokia, IBM, Sony, EA, Freescale, TI,...
- ▶ **OpenCL C for Compute Kernels: Derived from ISO C99**
  - ▶ Restrictions: recursion, function pointers, ...
  - ▶ Built-in data types/ functions
- ▶ **Timeline**
  - ▶ Jun'08: Launched, “strawman”
  - ▶ Dec'08: OpenCL 1.0 specification
  - ▶ Jun'10: OpenCL 1.1 specification
  - ▶ Nov'11: OpenCL 1.2 specification
  - Goal: a new OpenCL every 18 months

► SAXPY = Single-precision real Alpha X Plus Y:  $\vec{y} = \alpha \cdot \vec{x} + \vec{y}$

```
void saxpyCPU(int n, float a, float *x, float *y) {
    for (int i = 0; i < n; ++i)
        y[i] = a*x[i] + y[i];
}

int main(int argc, const char* argv[]) {
    int n = 10240; float a = 2.0f;
    float* x; float* y;
    x = (float*) malloc(n * sizeof(float));
    y = (float*) malloc(n * sizeof(float));

    // Initialize x, y
    for(int i=0; i<n; ++i){
        x[i]=i;
        y[i]=5.0*i-1.0;
    }

    // Invoke serial SAXPY kernel
    saxpyCPU(n, a, x, y);

    free(x); free(y);
    return 0;
}
```

## ▶ Review: SAXPY for GPUs (CUDA C)

```
__global__ void saxpy_parallel(int n,
    float a, float *x, float *y)
{
    int i = blockIdx.x * blockDim.x +
    threadIdx.x;
    if (i < n){
        y[i] = a*x[i] + y[i];
    }
}

int main(int argc, char* argv[])
{
    int n = 10240;
    float* h_x,*h_y; // Pointer to CPU memory
    // Allocate and initialize h_x and h_y

    float *d_x,*d_y; // Pointer to GPU memory
    cudaMalloc(&d_x, n*sizeof(float));
    cudaMalloc(&d_y, n*sizeof(float));
    cudaMemcpy(d_x, h_x, n * sizeof(float),
        cudaMemcpyHostToDevice);
    cudaMemcpy(d_y, h_y, n * sizeof(float),
        cudaMemcpyHostToDevice);

    // Invoke parallel SAXPY kernel
    dim3 threadsPerBlock(128);
    dim3 blocksPerGrid(n/threadsPerBlock.x);
    saxpy_parallel<<<blocksPerGrid,
        threadsPerBlock>>>(n, 2.0, d_x, d_y);

    cudaMemcpy(h_y, d_y, n * sizeof(float),
        cudaMemcpyDeviceToHost);

    cudaFree(d_x);
    cudaFree(d_y);
    free(h_x);
    free(h_y);
    return 0;
}
```

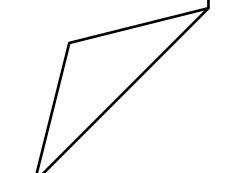
## ► Outlook: SAXPY for GPUs (OpenCL)

```

#include <stdio.h>
#include <CL/cl.h>
const char* source[] = {
    "__kernel void saxpy_opencl(int n, float a, __global float*
        x, __global float* y)",
    "{",
    "    int i = get_global_id(0);",
    "    if( i < n ){
        "        y[i] = a * x[i] + y[i];",
    "    }",
    "}"
};

int main(int argc, char* argv[]) {
    int n = 10240;  float a = 2.0;
    float* h_x, *h_y; // Pointer to CPU memory
    h_x = (float*) malloc(n * sizeof(float));
    h_y = (float*) malloc(n * sizeof(float));
    // Initialize h_x and h_y
    for(int i=0; i<n; ++i){
        h_x[i]=i; h_y[i]=5.0*i-1.0;
    }
    // Get an OpenCL platform
    cl_platform_id platform;
    clGetPlatformIDs(1,&platform, NULL);
    // Create context
    cl_device_id device;
    clGetDeviceIDs(platform, CL_DEVICE_TYPE_GPU, 1, &device,
        NULL);
    cl_context context = clCreateContext(0, 1, &device, NULL,
        NULL, NULL);
    // Create a command-queue on the GPU device
    cl_command_queue queue = clCreateCommandQueue(context,
        device, 0, NULL);
    // Create OpenCL program with source code
    cl_program program = clCreateProgramWithSource(context, 7, source,
        NULL, NULL);
    // Build the program
    clBuildProgram(program, 0, NULL, NULL, NULL, NULL);
    // Allocate memory on device on initialize with host data
    cl_mem d_x = clCreateBuffer(context, CL_MEM_READ_ONLY |
        CL_MEM_COPY_HOST_PTR, n*sizeof(float), h_x, NULL);
    cl_mem d_y = clCreateBuffer(context, CL_MEM_READ_WRITE |
        CL_MEM_COPY_HOST_PTR, n*sizeof(float), h_y, NULL);
    // Create kernel: handle to the compiled OpenCL function
    cl_kernel saxpy_kernel = clCreateKernel(program, "saxpy_opencl",
        NULL);
    // Set kernel arguments
    clSetKernelArg(saxpy_kernel, 0, sizeof(int), &n);
    clSetKernelArg(saxpy_kernel, 1, sizeof(float), &a);
    clSetKernelArg(saxpy_kernel, 2, sizeof(cl_mem), &d_x);
    clSetKernelArg(saxpy_kernel, 3, sizeof(cl_mem), &d_y);
    // Enqueue kernel execution
    size_t threadsPerWG[] = {128};
    size_t threadsTotal[] = {n};
    clEnqueueNDRangeKernel(queue, saxpy_kernel, 1, 0, threadsTotal,
        threadsPerWG, 0,0,0);
    // Copy results from device to host
    clEnqueueReadBuffer(queue, d_y, CL_TRUE, 0, n*sizeof(float), h_y,
        0, NULL, NULL);
    // Cleanup
    clReleaseKernel(saxpy_kernel);
    clReleaseProgram(program);
    clReleaseCommandQueue(queue);
    clReleaseContext(context);
    clReleaseMemObject(d_x); clReleaseMemObject(d_y);
    free(h_x); free(h_y); return 0;
}

```



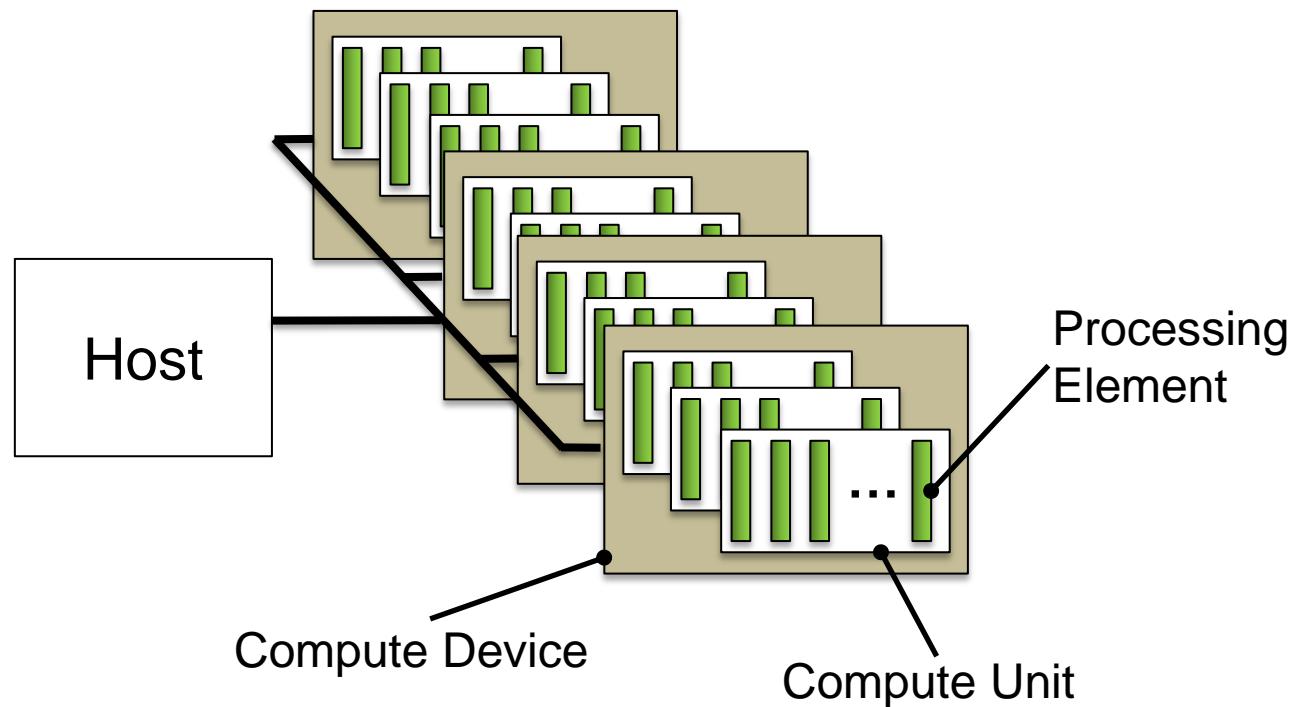
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- ▶ Platform Model
- ▶ Execution
- ▶ Memory Model
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- ▶ Tools & Libs

- ▶ **Data parallel**
  - ▶ Sequence of instructions is applied to multiple data elements
  - ▶ Hierarchical data parallel programming model
- ▶ **Task parallel**
  - ▶ Single instance of kernel executes e.g. multiple tasks
- ▶ **Hybrids possible**
- ▶ **SPMD = Single program multiple data**

CUDA	OpenCL
Pointer (host)	Handles (host)
Pointer (device)	Pointer (device)
CUDA C Runtime API less verbose	Verbose (similar to CUDA C Driver API)
Offline compilation	JIT

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CUDA	OpenCL
Core	Processing Element (PE)
Multiprocessor	Compute Unit (CU)
GPU/ Device	Compute Device



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- ▶ **Host-directed execution model**

- ▶ Executes kernel on device

- ▶ **Work-items are grouped into work-groups**

- ▶ Synchronization within work-group possible

- ▶ **Kernel executes for each work-item within an *index space***

- ▶ *NDRange* = n-dimensional index space

- ▶ **Indices** (examples for one dimension)

CUDA	OpenCL
Thread	Work-Item
Block	Work-Group
Grid	Index Space/ NDRange

CUDA	OpenCL
<code>threadIdx.x</code>	<code>get_local_id(0)</code>
<code>blockIdx.x</code>	<code>get_group_id(0)</code>
<code>blockIdx.x*blockDim.x+threadIdx.x</code>	<code>get_global_id(0)</code>
<code>blockDim.x</code>	<code>get_local_size(0)</code>
<code>gridDim.x</code>	<code>get_num_groups(0)</code>
<code>blockDim.x*gridDim.x</code>	<code>get_global_size(0)</code>

Work-Item

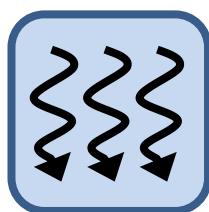


Processing Element

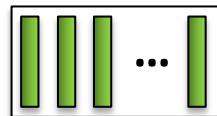


- ▶ Each work-item is executed by a processing element

Work-Group

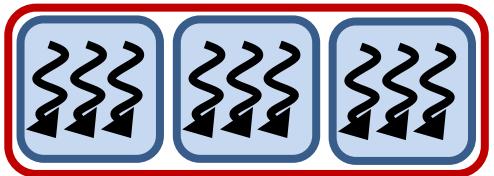


Compute Unit

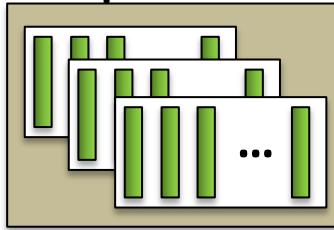


- ▶ Each work-group is executed on a compute unit
- ▶ Several concurrent work-groups can reside on one compute unit depending on memory resources

Index Space (Kernel)



Compute Device



- ▶ Each kernel is executed on a compute device

- ▶ **Setup GPU (e.g. driver)**
- ▶ **Download + install OpenCL libraries**  
Nvidia (GPU), AMD (GPU+CPU), Intel (CPU),... (cf. “Links” section)
- ▶ **OpenCL API**  
(cf. “Links” section)

green = background information  
OpenCL

- ▶ **Includes**  
`#include <CL/opencl.h>`
- ▶ **Compiling + linking**  
Use default Intel Compiler                          or                          *# on our cluster*  
`module switch intel gcc`                          *# on our cluster*  
`$CXX saxpy.cl -lOpenCL`                          *# \$CXX: e.g. icpc or g++*

## ▶ Kernel code

- ▶ Function qualifier: `__kernel`
- ▶ IDs: `get_global_id(dim)`, `get_local_id(dim)`, `get_group_id(dim)`
- ▶ Save as char array or read in from file

## ▶ Kernel usage

- ▶ Create program handle from kernel code: Just-In-Time (JIT) compilation

```
cl_program program = clCreateProgramWithSource (context,  
                                              srcSize, source,..., err);  
  
clBuildProgram(program,..., options,...);
```

options, e.g.:  
-D name #preprocessor  
-cl-fast-relaxed-math

- ▶ Create kernel handle

```
cl_kernel kernel = clCreateKernel(program,kernelName,err);
```

- ▶ Set kernel arguments

```
clSetKernelArg(kernel, argIdx, argSize, argVal);
```

# Example SAXPY: Kernel

```
const char* source[] = {
    "__kernel void saxpy_opencl(int n, float a,__global const float* x, __global
                                float* y)",
    "{",
        "    int i = get_global_id(0);",
        "    if( i < n ){
            "        y[i] = a * x[i] + y[i];",
        }",
    "}"
};
```

# Example SAXPY: Kernel usage

```
int main(int argc, char* argv[]) {  
    [...]  
    // Create OpenCL program with source code  
    cl_program program = clCreateProgramWithSource(context, 7, source, NULL, NULL);  
  
    // Build the program (JIT)  
    clBuildProgram(program, 0, NULL, NULL, NULL, NULL);  
  
    // Create kernel: handle to the compiled OpenCL function  
    cl_kernel saxpy_kernel = clCreateKernel(program, "saxpy_opencl", NULL);  
  
    // Set kernel arguments  
    clSetKernelArg(saxpy_kernel, 0, sizeof(int), &n);  
    clSetKernelArg(saxpy_kernel, 1, sizeof(float), &a);  
    clSetKernelArg(saxpy_kernel, 2, sizeof(cl_mem), &d_x);  
    clSetKernelArg(saxpy_kernel, 3, sizeof(cl_mem), &d_y);  
    [...]  
}
```

▶ **Context**

- ▶ Includes i.a. devices

▶ **Command Queue**

- ▶ Assigned to single device within a context

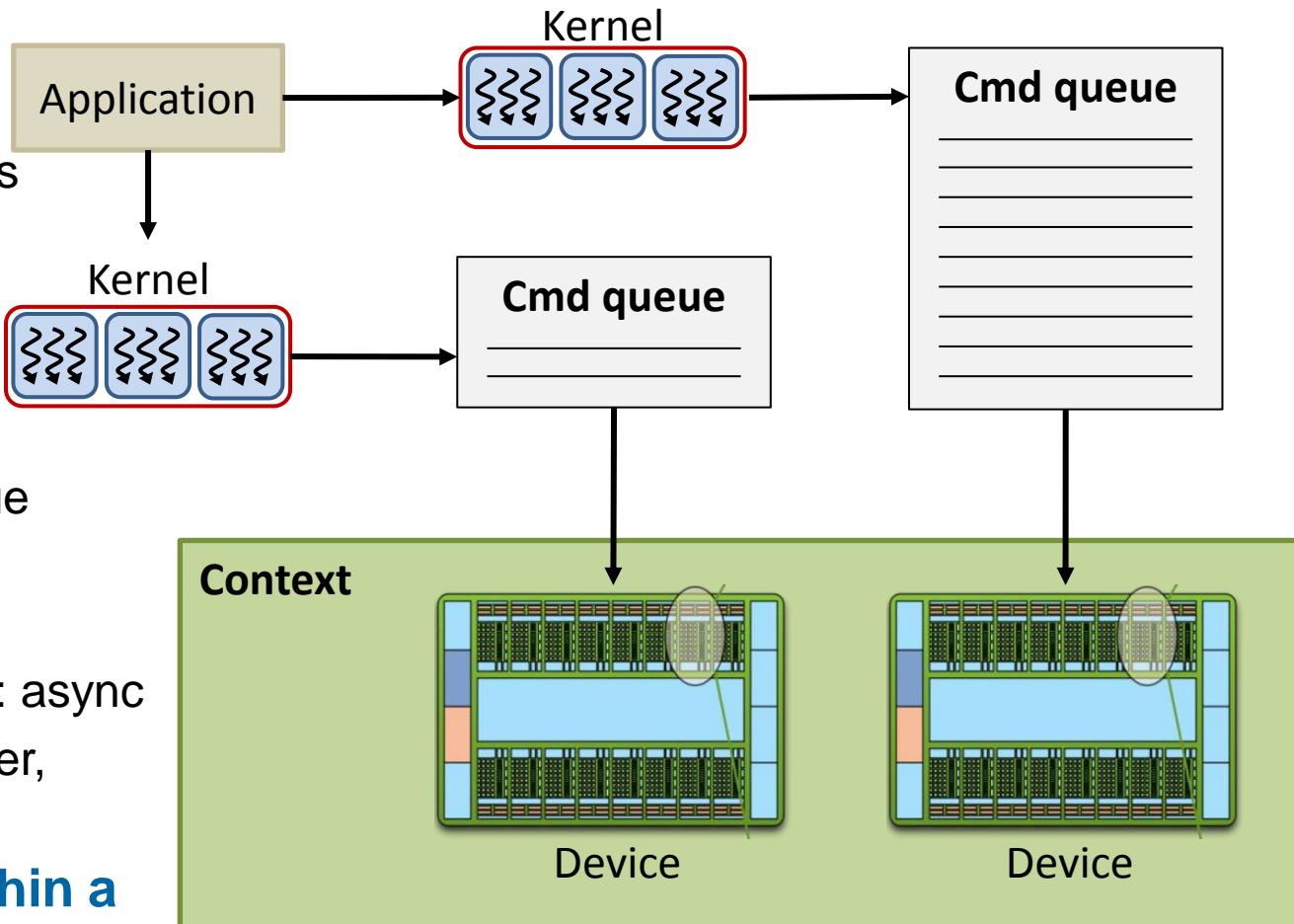
- ▶ Commands in queue are executed

→ Scheduling

- Host ⇔ Device: async
- Relative: in-order, out-of-order

▶ **Multiple queues within a single context possible**

▶ **Synchronization between commands enqueued to command-queue(s) in single context possible**



- ▶ Request platform

```
cl_platform platform;  
clGetPlatformIDs(1, &platform, ...)
```

- ▶ Request device

```
cl_device_id device;  
clGetDeviceIDs(platform, type, 1,&device,...)
```

type, e.g.:  
CL\_DEVICE\_TYPE\_GPU  
CL\_DEVICE\_TYPE\_CPU  
CL\_DEVICE\_TYPE\_ALL

- ▶ Create context

```
cl_context context = clCreateContext(...,1, &device,...)
```

- ▶ Create command queue

```
cl_command_queue queue = clCreateCommandQueue(context,  
                                              device, props, err)
```

props, e.g.:  
CL\_QUEUE\_OUT\_OF\_ORDER\_  
EXEC\_MODE\_ENABLE  
(default: in-order)

- ▶ Execute kernel

```
clEnqueueNDRangeKernel(queue, kernel, numDims,..., gridDims,  
                      blockDims,...)  
(clFinish(queue))
```

# Example SAXPY: Context & Queue

```
int main(int argc, char* argv[]) {
    [...]
    // Get an OpenCL platform
    cl_platform_id platform;
    clGetPlatformIDs(1, &platform, NULL);

    // Create context
    cl_device_id device;
    clGetDeviceIDs(platform, CL_DEVICE_TYPE_GPU, 1, &device, NULL);
    cl_context context = clCreateContext(0, 1, &device, NULL, NULL, NULL);

    // Create a command-queue on the GPU device
    cl_command_queue queue = clCreateCommandQueue(context, device, 0, NULL);

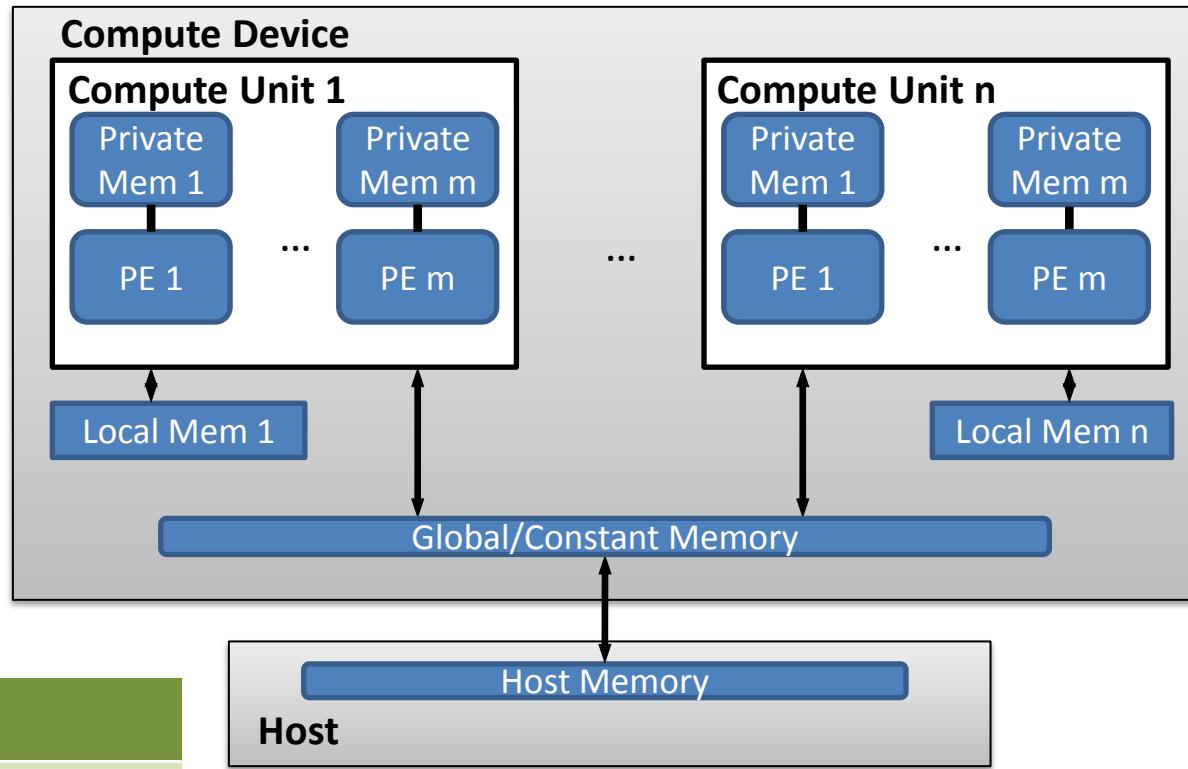
    // Create kernel, set kernel arguments [...]
    // Enqueue kernel execution
    size_t threadsPerWG[] = {128};
    size_t threadsTotal[] = {n}; // work items

    clEnqueueNDRangeKernel(queue, saxpy_kernel, 1, 0, threadsTotal, threadsPerWG,
        0,0,0);
    [...]
}
```

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# Memory model

- ▶ **Work-Item**
  - ▶ *Private* memory
- ▶ **Work-Group**
  - ▶ *Local* memory:
- ▶ **Kernel/ application**
  - ▶ *Constant* memory
  - ▶ *Global* memory



CUDA	OpenCL
Local memory	Private memory
Shared memory	Local memory
Constant memory	Constant memory
Global memory	Global memory

Attention! Difference!

## ▶ Kernel code

- ▶ Address space qualifiers: `__global`, `__constant`, `__local`, `__private`
- ▶ Used in: Variable declarations, function arguments

## ▶ Memory management

```
cl_mem buf = clCreateBuffer(context, memFlags, bufferSize,  
pointerToCPUMem, err)  
  
clReleaseMemObject(buf)
```

memFlags, e.g.:  
`CL_MEM_READ_WRITE`,  
`CL_MEM_WRITE_ONLY`,  
`CL_MEM_READ_ONLY`,  
`CL_MEM_COPY_HOST_PTR`

## ▶ Memory transfer CPU – GPU

“→” `clEnqueueWriteBuffer(queue, buf, blocking, ..., bufferSize,`  
`pointerToCPUMem, ...)`

blocking:  
`CL_TRUE`: blocking,  
`CL_FALSE`: non-blocking

“←” `clEnqueueReadBuffer(queue, buf, blocking, ..., bufferSize,`  
`pointerToCPUMem, ...)`

# Example SAXPY: Memory

```
const char* source[] = {
"__kernel void saxpy_opencl(int n, float a,__global const float* x, __global
                           float* y)", [...]}

int main(int argc, char* argv[]) {
[...]
float* h_x, *h_y; // Pointer to CPU memory
h_x=(float*) malloc(n*sizeof(float)); h_y=(float*) malloc(n*sizeof(float));
// Initialize h_x and h_y
// Create context, command queue, program, kernel

// Allocate memory on device on initialize with host data
cl_mem d_x = clCreateBuffer(context, CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
    n*sizeof(float), h_x, NULL);
cl_mem d_y = clCreateBuffer(context, CL_MEM_READ_WRITE | CL_MEM_COPY_HOST_PTR,
    n*sizeof(float), h_y, NULL);
// Execute kernel

// Copy results from device to host
clEnqueueReadBuffer(queue, d_y, CL_TRUE, 0, n*sizeof(float), h_y, 0, NULL,
    NULL);
[...]
}
```

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<b>Platform model</b>	
* Core	Processing Element (PE)
** Multiprocessor	Compute Unit (CU)
*** GPU/ Device	Compute Device
<b>Execution model</b>	
* Thread	Work-Item
** Block	Work-Group
*** Grid	Index Space/ NDRange
<b>Memory model</b>	
* Local memory	Private memory
** Shared memory	Local memory
*** Global memory	Global memory

Stars map hardware, (logical) execution unit and memory space

## ► 5 steps for a basic program with OpenCL

```
#include <stdio.h>
#include <CL/cl.h>
const char* source[] = {
    "__kernel void saxpy_opencl(int n, float a, __global float*
        x, __global float* y)",
    "{",
    "    int i = get_global_id(0);",
    "    if( i < n ){
        "        y[i] = a * x[i] + y[i];",
    "    }",
    "}"
};

int main(int argc, char* argv[]) {
    int n = 10240;  float a = 2.0;
    float* h_x, *h_y; // Pointer to CPU memory
    h_x = (float*) malloc(n * sizeof(float));
    h_y = (float*) malloc(n * sizeof(float));
    // Initialize h_x and h_y
    for(int i=0; i<n; ++i){
        h_x[i]=i; h_y[i]=5.0*i-1.0;
    }

    // Get an OpenCL platform
    cl_platform_id platform;
    cl_context context = clCreateContext(0, 1, &device, NULL,
        NULL, NULL);
    // Create a command-queue on the GPU device
    cl_command_queue queue = clCreateCommandQueue(context,
        device, 0, NULL);
}
```

### 1. Define the platform (= devices + context + queues)

```
// Build the program
clBuildProgram(program, 0, NULL, NULL, NULL, NULL);

// Allocate memory on device on initialize with host data
CL MEM COPY HOST PTR, n*sizeof(float), h_y, NULL);
// Create kernel: handle to the compiled OpenCL function
clSetKernelArg(saxpy_kernel, 1, sizeof(float), &a);
clSetKernelArg(saxpy_kernel, 2, sizeof(cl_mem), &d_x);
clSetKernelArg(saxpy_kernel, 3, sizeof(cl_mem), &d_y);

// Enqueue kernel execution
clEnqueueKernel(queue, 1, &saxpy_kernel, 0, NULL, NULL);

// Cleanup
clReleaseKernel(saxpy_kernel);
clReleaseProgram(program);
clReleaseCommandQueue(queue);
clReleaseContext(context);
clReleaseMemObject(d_x); clReleaseMemObject(d_y);
free(h_x); free(h_y); return 0;
```

### 2. Create + built the program

### 3. Setup memory objects

### 4. Define kernel (attach kernel function to arguments)

### 5. Submit commands: move memory objects and execute kernels

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## ▶ Debugger

- ▶ gDebugger GPU (memory) debugger, Windows (currently), integrated in Visual Studio, AMD (currently free of charge)
- ▶ Intel Debugger CPU debugger, Windows, integrated in Visual Studio, Intel (free of charge)

## ▶ Profiling/ tracing

- ▶ Visual Profiler Performance analysis w/ HW counters, NVIDIA (free of charge)
- ▶ Parallel Nsight API & kernel tracing, Windows, integrated in Visual Studio, NVIDIA (free of charge)
- ▶ VampirTrace Performance monitoring (tracing), TU Dresden

- ▶ **ViennaCL**      Linear algebra: BLAS, FFT, iterative solvers
- ▶ **ArrayFire**      E.g. sort, sum
- ▶ **Upcoming**
  - ▶ MAGMA      Dense linear algebra (subset of BLAS, LAPACK)