## Programming OpenMP

## Vectorization (SIMD)

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## Vectorization

- SIMD = Single Instruction Multiple Data
$\rightarrow$ Special hardware instructions to operate on multiple data points at once
$\rightarrow$ Instructions work on vector registers
$\rightarrow$ Vector length is hardware dependent

Sequential

$c$
Sequential

| Step 1 | Step 2 Step 3 | Step 4 |  |
| :---: | :---: | :---: | :---: |
| $\mathrm{b}[0]$ | $\mathrm{b}[1]$ | $\mathrm{b}[2]$ | $\mathrm{b}[3]$ |
| + | + | + | + |
| $\mathrm{c}[0]$ | $\mathrm{c}[1]$ | $\mathrm{c}[2]$ | $\mathrm{c}[3]$ |
| $=$ | $=$ | $=$ | $=$ |
| $\mathrm{a}[0]$ | $\mathrm{a}[1]$ | $\mathrm{a}[2]$ | $\mathrm{a}[3]$ |

Vectorized

| Step 1 | Step 2 |
| :---: | :---: |
| $\mathrm{b}[0], \mathrm{b}[1]$ | $\mathrm{b}[2], \mathrm{b}[3]$ |
| + | + |
| $\mathrm{c}[0], \mathrm{c}[1]$ | $\mathrm{c}[2] \mathrm{c}[3]$ |
| $=$ | $=$ |
| $\mathrm{a}[0], \mathrm{a}[1]$ | $\mathrm{a}[2], \mathrm{a}[3]$ |

## Vectorization

- Vector lengths on Intel architectures
$\rightarrow 128$ bit: SSE = Streaming SIMD Extensions

$\rightarrow 256$ bit: AVX = Advanced Vector Extensions

$\rightarrow 512$ bit: AVX-512



## Data Alignment

- Vectorization works best on aligned data structures.



## Approaches to Vectorization

Compiler
auto-vectorization
Explicit Vector Programming
$($ e.g. with OpenMP)

Inline Assembly
(e.g.)

Assembler Code
(e.g. addps, mulpd, ...)


## Data Dependencies

## Data Dependencies

■ Suppose two statements S1 and S2
$■$ S2 depends on S1, iff S1 must execute before S2
$\rightarrow$ Control-flow dependence
$\rightarrow$ Data dependence
$\rightarrow$ Dependencies can be carried over between loop iterations
■ Important flavors of data dependencies
FLOW
$s 1: a=40$
$b=21$
$s 2: c=a+2$

$$
\begin{aligned}
& \text { ANTI } \\
& b=40 \\
& \mathrm{~s} 1: \mathrm{a}=\mathrm{b}+1 \\
& \mathrm{~s} 2: \mathrm{b}=21
\end{aligned}
$$

## Loop-Carried Dependencies

## OpenMP

■ Dependencies may occur across loop iterations
$\rightarrow$ Loop-carried dependency
■ The following code contains such a dependency:

```
void lcd_ex(float* a, float* b, size_t n, float c1, float c2)
{
    size_t i;
    for (i = 0; i < n; i++) {
        a[i] = c1 * a[i + 17] + c2 * b[i];
    }
}

■ Some iterations of the loop have to
\(\rightarrow\) Simple trick: Can you reverse the loop w/o getting wrong results?

\section*{Loop-carried Dependencies}

\section*{■ Can we parallelize or vectorize the loop?}
```

void lcd_ex(float* a, float* b, size_t n, float c1, float c2) {
for (int i = 0; i < n; i++) {
a[i] = c1 * a[i + 17] + c2 * b[i];
} }

```

\(\rightarrow\) Parallelization: no
(except for very specific loop schedules)
\(\rightarrow\) Vectorization: yes
(iff vector length is shorter than any distance of any dependency)

\section*{The OpenMP SIMD constructs}

\section*{The SIMD construct}
- The SIMD construct enables the execution of multiple iterations of the associated loops concurrently by means of SIMD instructions.
```

C/C++:
\#pragma omp simd [clause(s)]
for-loops

```

Fortran:
!\$omp simd [clause(s)] do-loops
[!\$omp end simd]
- where clauses are:
\(\rightarrow\) linear(list[:linear-step]), a variable increases linearly in every loop iteration
\(\rightarrow\) aligned(list[:alignment]), specifies that data is aligned
\(\rightarrow\) private(list), as usual
\(\rightarrow\) lastprivate(list) , as usual
\(\rightarrow\) reduction(reduction-identifier:list) , as usual
\(\rightarrow\) collapse( \(n\) ), collapse loops first, and than apply SIMD instructions

\section*{The SIMD construct}

\section*{OpenMP}
- The safelen clause allows to specify a distance of loop iterations where no dependencies occur.
\begin{tabular}{|c|c|c|c|}
\hline & Sequential & \multicolumn{2}{|l|}{Vector length 128-bit} \\
\hline & Step 1 Step 2 Step 3 Step 4 & Step 1 & Step 2 \\
\hline double a[6],b[6]; ... & a[0] \(\quad\) a[1] \(\quad\) a[2] \(a[3]\) & a[0], a[1] & a[2],a[3] \\
\hline \[
\text { for }(\mathrm{i}=2 ; \mathrm{i}<6 ; \mathrm{i}++)
\] &  & b[2] b[3] &  \\
\hline \[
\begin{array}{ll}
\{ & a[i]=a[i-2]^{*} b[i] \\
\}
\end{array}
\] &  & b[2],b[3] & b[4],b[5] \\
\hline & \(a[2] ~ a[3] ~ a[4] ~ a[5] ~\) & a[2],a[3] & a[4],a[5] \\
\hline
\end{tabular}

\section*{The SIMD construct}
- The safelen clause allows to specify a distance of loop iterations where no dependencies occur.

Vector length 128-bit
\begin{tabular}{|c|}
\hline double a[6],b[6]; \\
\hline ... \\
\hline for(i=2 ; i < 6 ; i++) \\
\hline \[
a[i]=a[i-2] * b[i] ;
\] \\
\hline \} \\
\hline
\end{tabular}


Vector length 256-bit

- Any vector length smaller than or equal to the length specified by safelen can be chosen for vectorizaion.
- In contrast to parallel for/do loops the iterations are executed in a specified order.

\section*{The loop SIMD construct}
- The loop SIMD construct specifies a loop that can be executed in parallel by all threads and in SIMD fashion on each thread.
```

C/C++:
\#pragma omp for simd [clause(s)]
for-loops

```
```

Fortran:
!$omp do simd [clause(s)]
    do-loops
[!$omp end do simd [nowait]]

```
- Loop iterations are first distributed across threads, then each chunk is handled as a SIMD loop.
- Clauses:
\(\rightarrow\) All clauses from the loop- or SIMD-construct are allowed
\(\rightarrow\) Clauses which are allowed for both constructs are applied twice, once for the threads and once for the SIMDization.

\section*{The declare SIMD construct}
- Function calls in SIMD-loops can lead to bottlenecks, because functions need to be executed serially.


Solutions:
- avoid or inline functions
- create functions which work on vectors instead of scalars

\section*{The declare SIMD construct}

\section*{Open
or more}
- Enables the creation of multiple versions of a function or subroutine where one or more versions can process multiple arguments using SIMD instructions.
```

C/C++:
\#pragma omp declare simd [clause(s)]
[\#pragma omp declare simd [clause(s)]]
function definition / declaration

```

Fortran:
!\$omp declare simd (proc_name)[clause(s)]
- where clauses are:
\(\rightarrow\) simdlen(length), the number of arguments to process simultanously
\(\rightarrow\) linear(list[:linear-step]), a variable increases linearly in every loop iteration
\(\rightarrow\) aligned(argument-list[:alignment]), specifies that data is aligned
\(\rightarrow\) uniform(argument-list), arguments have an invariant value
\(\rightarrow\) inbranch / notinbranch, function is always/never called from within a conditional statement

File: f.c
\#pragma omp declare simd double f(double x)
\{
return (4.0 / (1.0 + \(\left.\mathrm{x}^{*} x\right)\) );
\}
File: pi.c
\#pragma omp declare simd double f(double x);
...
\#pragma omp simd linear(i) private(fX)
reduction(+:fSum)
for ( \(\mathrm{i}=0 ; \mathrm{i}<\mathrm{n} ; \mathrm{i}++\) )
\{
\(\mathrm{fX}=\mathrm{fH}\) * ((double) \(\mathrm{i}+0.5)\);
fSum += f(fX);
\}
return fH * fSum;

Calculating Pi with numerical integration of:
\[
\pi=\int_{0}^{1} \frac{4}{1+x^{2}}
\]


\section*{Example: Pi}

\section*{Runtime of the benchmark on:}
\(\rightarrow\) Westmere CPU with SSE (128-bit vectors)
\(\rightarrow\) Intel Xeon Phi with AVX-512 (512-bit vectors)
\begin{tabular}{|c|c|c|c|c|}
\hline & \begin{tabular}{l} 
Runtime \\
Westmere
\end{tabular} & \begin{tabular}{l} 
Speedup \\
Westmere
\end{tabular} & \begin{tabular}{l} 
Runtime \\
Xeon Phi
\end{tabular} & \begin{tabular}{c} 
Speedup \\
Xeon Phi
\end{tabular} \\
\hline \begin{tabular}{c} 
non \\
vectorized
\end{tabular} & 1.44 sec & 1 & 16.25 sec & 1 \\
\hline vectorized & 0.72 sec & 2 & 1.82 sec & 8.9 \\
\hline
\end{tabular}

Note: Speedup for memory bound applications might be lower on both systems.```

